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ROBOTECH CONTROLLER 501

Advanced Robotics Computer



Introduction

The Conpleks Robotech Controller 501 is a compact high-performance, ruggedized embedded vehicle computer ideal for rough outdoor robotic applications.

The controller is equipped with a number of standardized interfaces such as CAN, RS232, USB and Ethernet making it easy to connect the controller to all relevant parts of your application.

The controller supports the Conpleks Robotech software based on a Linux/Ubuntu operating system, ROS-based middleware and robot application software.

Robotech Controller 501 Main Features

The Conpleks Robotech Controller 501 has a set of main functions and features that makes it very suitable for any outdoor, mobile robot and other outdoor automation applications. The main features are:

- On-board 3rd generation Intel Core i5 processor
- Flash-based hard-drive
- Linux/Ubuntu operating system
- Compact, ruggedized enclosure, fully sealed and IP67 compliant
- High quality connectors



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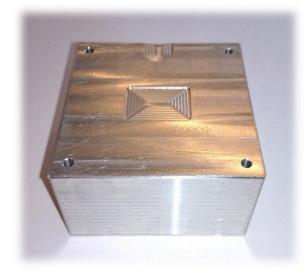
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In order to achieve an efficient cooling of the CPU, the heat is transferred directly to the enclosure through a high-quality and special designed heat-sink.



This way, the heat dissipated inside the CPU is transferred directly to the enclosure, and there is no need for venting holes or fans.

Monitoring and Maintenance

The Conpleks Robotech Controller 501 is equipped with four LEDs in order to monitor the overall operational status.



By using one of the available USB ports, it is possible to connect a local craft tool including laptops and USB memory sticks for instance for boot procedures maintenance.

Conpleks Robotech Controller Software

The Conpleks Robotech Controller 501 is pre-loaded with a Linux/Ubuntu support software package.

Optionally, Conpleks can install more advanced software such as real-time OSes with ROS-support and complete application specific software packages tailored to your specific needs.

Conpleks uses ROS-middleware, Robot Operating System, in order to efficiently develop and implement the software needed for various automation and robotics applications.

- ROS is an open-source robotics platform providing software tools and infrastructure for robotics development.
- ROS enables rapid development of prototypes with high reuse of already available components and provides a short path between state-of-theart research algorithms and production ready software.
- ROS is supported by a large community of both industrial companies and research institutions, which are all contributing to the ROS ecosystem.

The ROS-based middleware is fully integrated with the 501's hardware interfaces giving the basis needed for rapid prototyping and easy interfacing to existing systems.

Developers can easily connect own sensors and actuators and begin to code the application instead of worrying about device drivers and compatibility etc.

Rugged and Hardened Design

All operational interfaces are located on the same side of the controller, making it easy to install and fit the controller into almost any vehicle or other robotics application.

The controller enclosure is a rugged, powder painted, die cast aluminum box. The box cover lid is fastened by stainless screws and seals the box providing IP67 ingress protection.



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External Interfaces

The Conpleks Robotech Controller 501 is equipped with a number of IP67 compliant interface connectors, all on the same side of the unit.



The controller has as default the following connectors:

- 2 Ethernet ports (2 GE 4 pair)
- 2 USB 2.0 ports
- 4 Serial ports
- 12 VDC power (with ignition signal)
- 1 WiFi antenna port (optional)
- 1 Bluetooth antenna port (optional)
- 1 or 2 CAN ports (optional, replacing either Ethernet or serial ports using the M12 connector mounts)

Other port and connector configurations can be mounted on request.

Powerful Main Board

The Conpleks Robotech Controller 501 is equipped with a powerful Aaeon GENE-QM77 main CPU board that supports the 3rd Generation Intel® i7-,i5,-i3 multi-core CPU technology. Core i5 is the default.

Based on the Mobile 3rd generation Intel® chipset, the motherboard offers an ideal performance-perwatt ratio and the very latest interface technology The board features a CFAST slot, which allows the mounting of ultra-compact Flash disks for storage.

The motherboard also supports Intel Active Management Technology, Intel AMT 8.0, for remote management and easy maintenance, resulting in higher system availability and lower total costs.

Installation

The Robotech Controller 501 supports easy mounting in any outdoor, mobile robot application. By using four mounting screws, the unit can be securely fastened to the vehicle.

Please secure adequate cooling and use optional vibrations suppressors.





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Technical Specifications

GENERAL

- Advanced, high-performance, ruggedized, embedded computer platform
- Well suited for temperaturehardened outdoor robotics.
- Pre-loaded Linux/Ubuntu operating system
- Optional ROS-based middleware and application software
- Rugged mechanical enclosure, die casted powder-painted aluminum
- Passive cooling through the enclosure, no venting holes, no internal fans

MAIN BOARD

- Aaeon GENE-QM77
- 3rd generation Intel Core i5 processor, i5-3360M
- Flash-based hard-drive, CFAST
- 16 GB (32GB optional)
- RAM, 4 GB

RADIO OPTIONS

- WiFi supported according to
- IEEE 802.11a, IEEE 802.11b/g, IEEE 802.11n, 2.4 GHz,
- Client or AP mode (optional)
- Bluetooth v4.0 (optional)

MECHANICS

- Material: Aluminum
- Color: RAL 7001
- Cover screws: Stainless Steel
- Cover gasket: Neoprene
- Ingress Protection: IP67 (according to EN 60529)

DIMENSIONS

- LxWxH: 200 x 170 x 90 mm
- Weight: 2850 g

INTERFACES

- 2 Ethernet ports (2GE, 4 pair, M12)
- 2 USB ports (Samtec, sealed)
- 4 Serial ports (M12)
- 12 VDC (7/8 UFN)
- 1 WiFi antenna port (TNC, optional)
- 1 or 2 CAN ports (optional, replacing Ethernet or serial ports using the M12 connector mounts)
- 1 Bluetooth antenna port (optional)
- Other port and connector configurations are possible

POWER

- Power consumption: 20-40 W
- 12 VDC automotive power (with ignition signal)
- Wide operational input voltage range: 10-30 VDC (6 and 34 VDC shutdown limits)
- Intelligent shutdown controller
- On/off motherboard control
- <1.0mA standby current</p>

ELECTROMAGNETIC COMPATIBILITY

The Robotech Controller 501 is built to comply with the following:

- 2004/108/EC Electromagnetic Compatibility Directive (EMC)
- EN 55022:2010 (EMC)

ENVIRONMENTAL

Operational environment

- Temperature range +0°C to +40 °C at 100% CPU load
- Temperature range +0°C to +50 °C at 50% CPU load
- Humidity range 5% to 100 %
 RH, condensing

Storage (packaged)

- Temperature range -20°C to +55°C
- Humidity range 10% to 95% RH, non-condensing

RoHS compliance

The product meets the requirements in the European RoHS directive: 2011/65/EU, RoHS6.

End-of-life treatment – WEEE directive

 Requirements meeting the WEEE-directive (2002/96/EC)

